

Infineon XMC™ Microcontroller Co-Simulation

IPCEI on ME - Important Project of Common European Interest on Microelectronics

Infineon Technologies AG 2025-04-14





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IPCEI Homepage

https://www.infineon.com/cms/austria/en/IPCEI-on-ME







Infineon Technologies Austria – Part of IPCEI Microelectronics

Infineon's power semiconductors are deployed in key markets such as automotive, energy, digital and industrial equipment. These power electronics solutions also drive innovation in environmental sustainability, energy-efficiency and reduction of CO₂ emissions.

Infineon's IPCEI spillover activities include the following areas:

STEM education and talent
 Infineon Austria will actively involve educational institutions and STEM talent, from pupils to PhDs.





















Quick design of a flyback converter	28.11.2023	14:00 - 15:00	> More information
Application driven development Part I: USB-PowerDelivery	13.12.2023	14:00 - 15:00	> More information
Application driven development Part II: Embedded Coding	13.12.2023	15:00 - 16:00	> More information
Application driven development Part III: Cloud Co-Simulation	13.12.2023	16:00 - 17:00	> More information

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Driving decarbonization and digitalization. Together.





Semiconductors are crucial to solve the energy challenges of our time and shape the digital transformation.

This is why Infineon is committed to actively driving decarbonization and digitalization.

As a global semiconductor leader in power systems and IoT, we enable game-changing solutions for green and efficient energy, clean and safe mobility, as well as smart and secure IoT.

We make life easier, safer, and greener. Together with our customers and partners. For a better tomorrow.

Infineon is a global leader in power systems and IoT



Global leader

in automotive, power management, energy efficient technologies and IoT

~58,060 employees¹

Market position

Automotive

#1

TechInsights, April 2024 Power

#1

Omdia, October 2024 Microcontroller

¥1

Omdia, March 2025

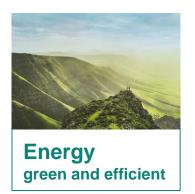


¹ As of 30 September 2024

Infineon at a glance



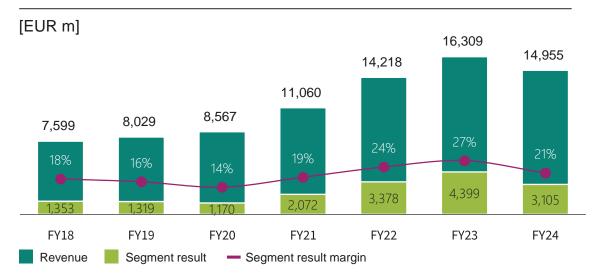
Growth areas







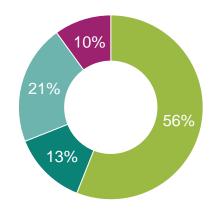
Financials



FY24 revenue by segment¹



- Green Industrial Power (GIP)
- Power & Sensor Systems (PSS)
- Connected Secure Systems (CSS)



EMEA

Employees¹

58,060 employees worldwide

71 R&D and

15 manufacturing locations²



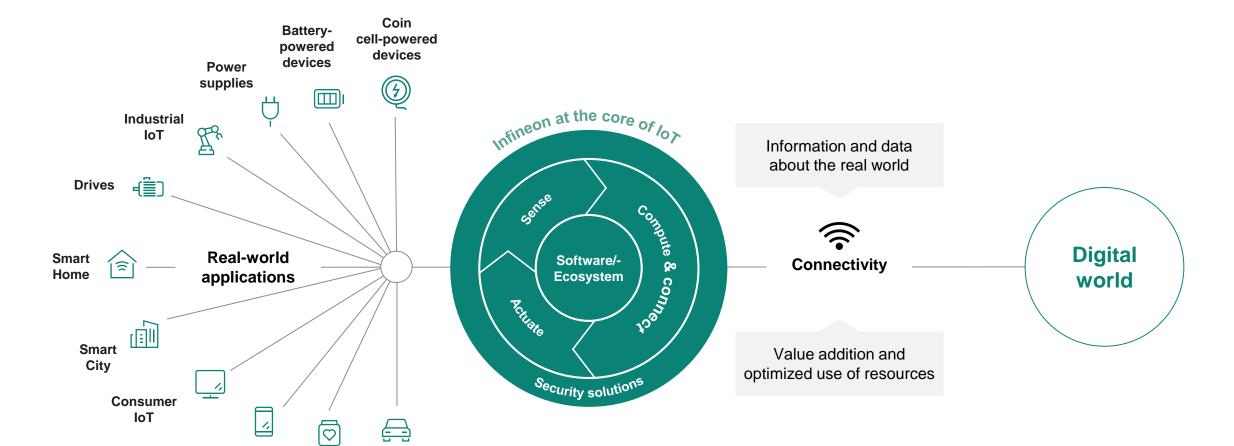
For further information: Infineon Annual Report.

1 2024 Fiscal year (as of 30 September 2024) | 2 As of 30 September 2024

[Owner: Infineon Technologies AG Doc ID: Infineon IPCEI-ME Webinar Microcontroller Co-Simulation Vers.: v1.0]

Infineon at the core of IoT – Driving digitalization by serving strongly growing multi-application markets





Sense: sensors | **Compute and connect:** microcontrollers, memories, Wi-Fi, Bluetooth, BLE, USB | **Actuate:** Power semiconductors

Smartphones

Health

care products

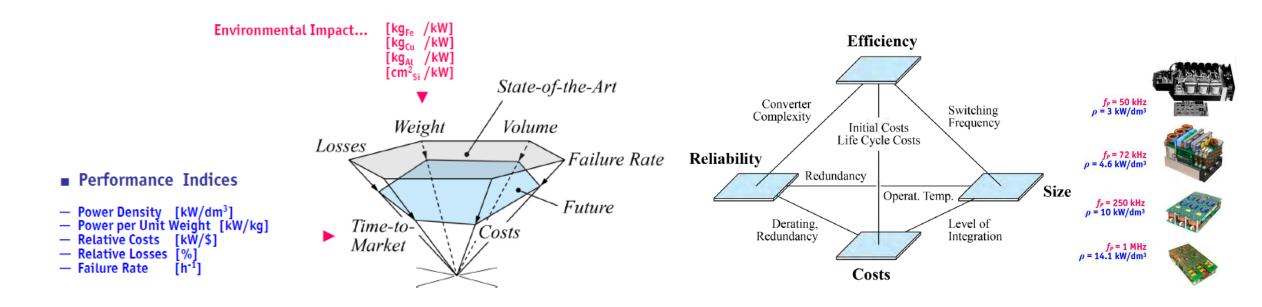
Automotive

Power Converter Optimization Challenge



Design Space Exploration

Trade-off Finding



[Burkart_Kolar1] Ralph M. Burkart & Johann W. Kolar: Tutorial Advanced Modeling and Multi-Objective
 Optimization / Evaluation of SiC Converter Systems, ETH Zurich, Power Electronic Systems Laboratory

Simulation Platforms: proven way to design-win

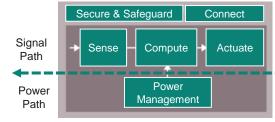


Selection

00

Offline











✓ green

connected

Sense

Does the sensor switch at the right

Compute

- Does my software run w/o errors?

Actuate

- What is the overall efficiency?
- Does my design not overheat?

Connect

Digital

world

Secure & Safeguard

- Is my solution safe?
- Is my solution secure?

Magnetic design

Software design (Controller)

Electrical design Thermal design

Software Design (Protocols, Safety/Security)

Sensor Tools

(3D, Angle & Hall sensors)

Infineon Designer (MOSFET, IGBT, Gate Driver IC, Voltage Regulator, Audio Class D, MCU)



LTspice* 17

IPOSIM (IGBT, Bipolar, SiC)

Motor Simulator (IGBT, IPM)

OPTIREG™ (PMIC)

PowerEsim (SMPS)



arm KEIL Studio





ModusToolbox™

AURIX™ Development Studio

https://softwaretools.infineon.com

Center

Developer

Infineon

TINA Spice, PSpice, SIMetrix, [LTspice¹]

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Infineon Designer - Online SPICE Engine

demonstrate the functionality of the prototyping engine with Arduino shields for > lighting and > motor control applications and

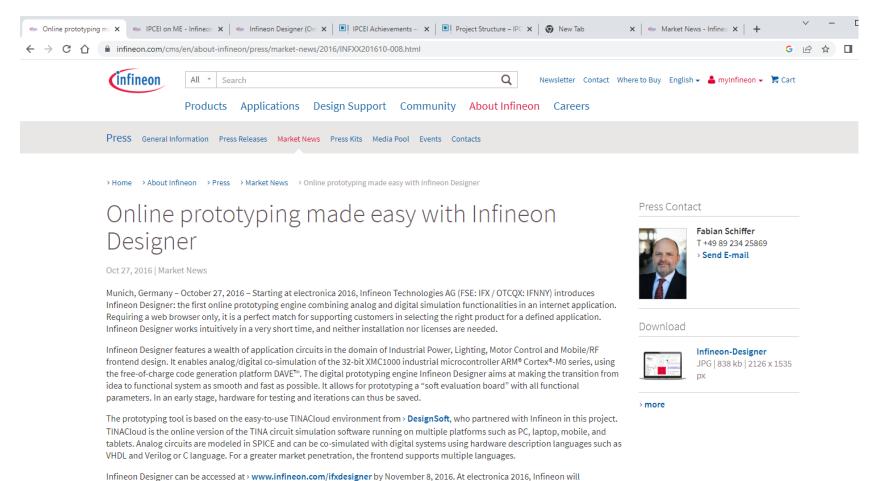
The world is getting smarter and more connected by the day. At electronica 2016 Infine on presents exciting demos and product solutions that are making tomorrow's cars, factories and homes smart, secure and energy-efficient. New products and demos can be discovered at

compare the results with real hardware. The demonstration is part of the "Maker's corner".

Infineon at electronica 2016 (November 8-11, 2016, Munich, Germany)



https://www.infineon.com/cms/en/about-infineon/press/market-news/2016/INFXX201610-008.html



- Launched at Electronica 2016
 - Online, no installation, no license fee, easy to use
 - 1000+ application circuits (lighting, power supplies, motor control, computing DC-DC PoL, audio etc.)
- Accurate transient and system
 efficiency simulation powered by TINA
 SPICE engine
- Full-featured circuit editor with Infineon SPICE library for free
- Export to Altium PCB design and export of the BoM (Bill of Materials)
- Fast parameter configuration with design tool for better evaluation experience
- Digital/analog co-simulation (e.g. Microcontroller code debugging)

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Infineon Designer Server Infrastructure www.infineon.com/ifxdesigner



Infineon Server

www.infineon.com/ifxdesigner



Demo mode

No registration needed (no circuit editor)
https://design.infineon.com/tinademo/designer.php

Expert mode

Please register <u>here</u> (full version):

https://design.infineon.com/tinaui/designer.php

Registration to myInfineon

https://www.infineon.com/cms/en/myInfineon/benefits/

DesignSoft Server

www.tinacloud.com

Upgrade





Online

Industrial version





TINA-TI SPICE-based analog simulation program Offline

2025-04-14

Infineon

Infineon Designer Features





- Component losses
- Component junction temperature
- Steady-state system efficiency

- Infineon product > footprints
- Passive component footprints
- Altium PCB project with schematic

- Detailed BoM including type, value, footprint, part number, description, manufacturer and more
- Export to excel or print to PDF
- Fast configuration of circuit variables and global parameters
- Individual function programming

- Support of XMC1000 family
- Instruction cycle accurate co-simulation including peripheral support
- ModusToolbox™ replacing
 DAVE™ IDE for code
 generation
- New: XMC4400 simulation

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Thermal & System Efficiency Simulation 24V Automotive Battery Switch Demonstrator



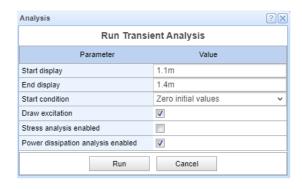


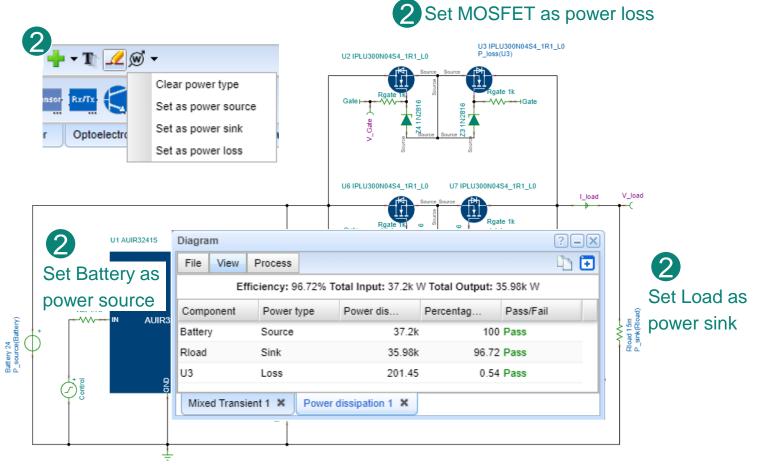


2. Check & set the power types of components



3. Set transient analysis and run simulation





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Export to Altium PCB

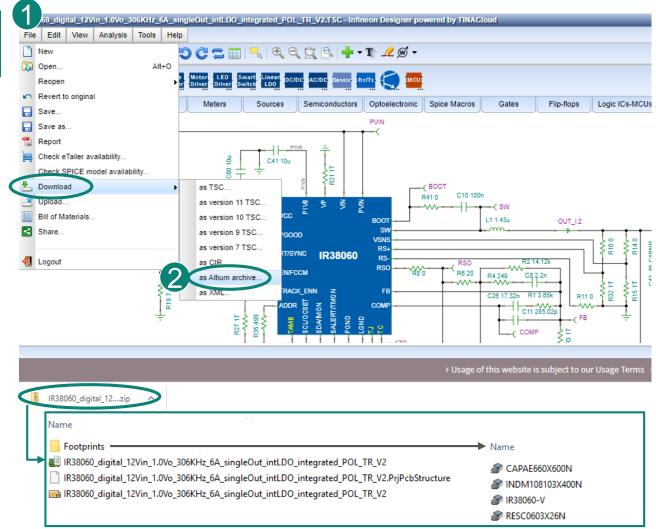
1.0V 6A Single Output Integrated PoL Solution IR38060







2. Download as Altium archive and check



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Export to Altium PCB

1.0V 6A Single Output Integrated PoL Solution IR38060



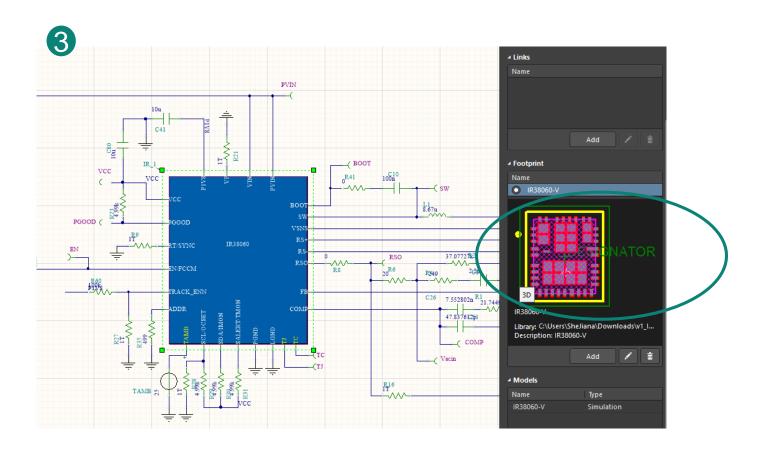
1. Open circuit and login with mylnfineon account



2. Download as Altium archive and check



3. Open project in Altium and start PCB design



Infineon Designer Features





- Component losses
- Component junction temperature
- Steady-state system efficiency

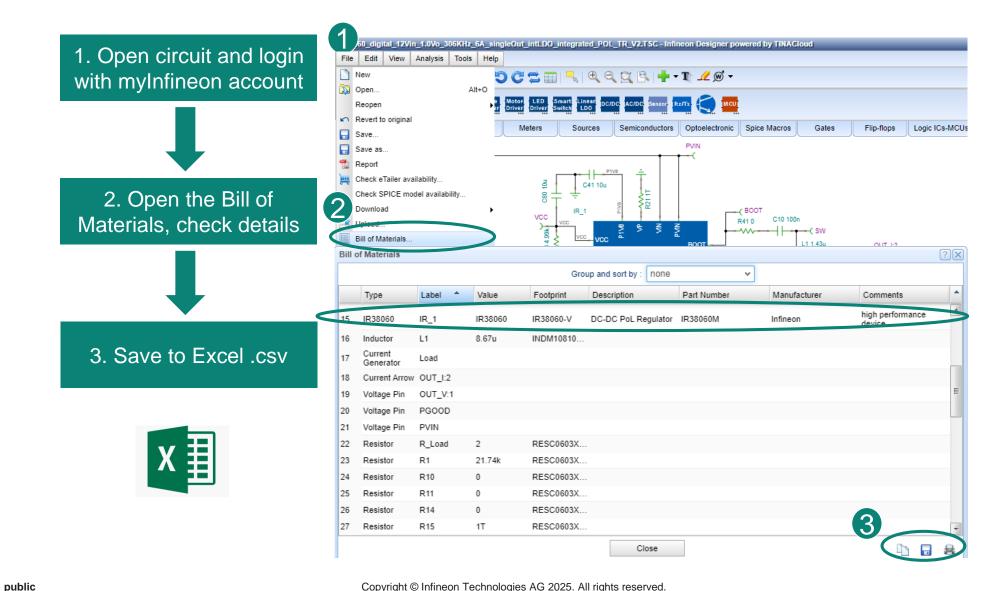
- Infineon product > footprints
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- > New: XMC4400 simulation

Export the Bill of Materials

1.0V 6A Single Output Integrated PoL Solution IR38060





Infineon Designer Features





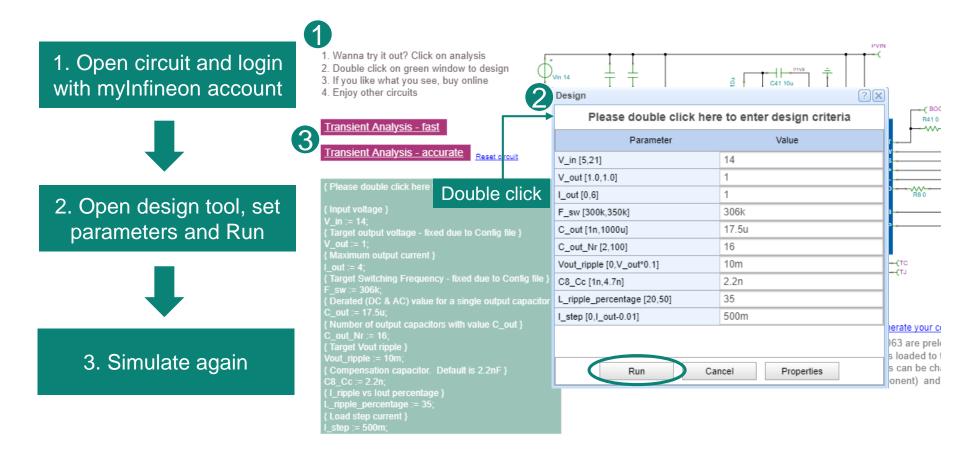
- Component losses
- Component junction temperature
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- Infineon product > footprints
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Use Design Tool - Parameter Setting & Calculation1.0V 6A Single Output Integrated PoL Solution IR38060





- Design Tool (advanced mode see appendix)
 - Easier parameter setting
 - Faster value calculation for all circuit components set by defined formulas & scripts

Infineon Designer Features





- Component losses
- Component junction temperature
- Steady-state system efficiency

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Digital Twin Circuit Simulation simulate first on virtual system before building the real hardware



build application code project in ModusToolbox™ or DAVE™ IDE

Simulation: Digital Twin

upload .elf .hex to simulator





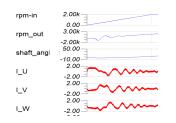
.elf .hex

co-simulate XMC™ w/ SPICE

- Value Proposition MCU co-simulation
- Time-to-market: start developing before you have the hardware kit
- Safety: test on virtual system will not harm engineer or destroy hardware
- Cost: exploration of design space cheaper than building hardware many times
- Security: CSS controller lack a debug interface so code debugging can be only



run on real hardware kit

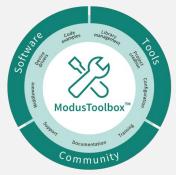


Real System





https://www.Infineon.com/modustoolbox



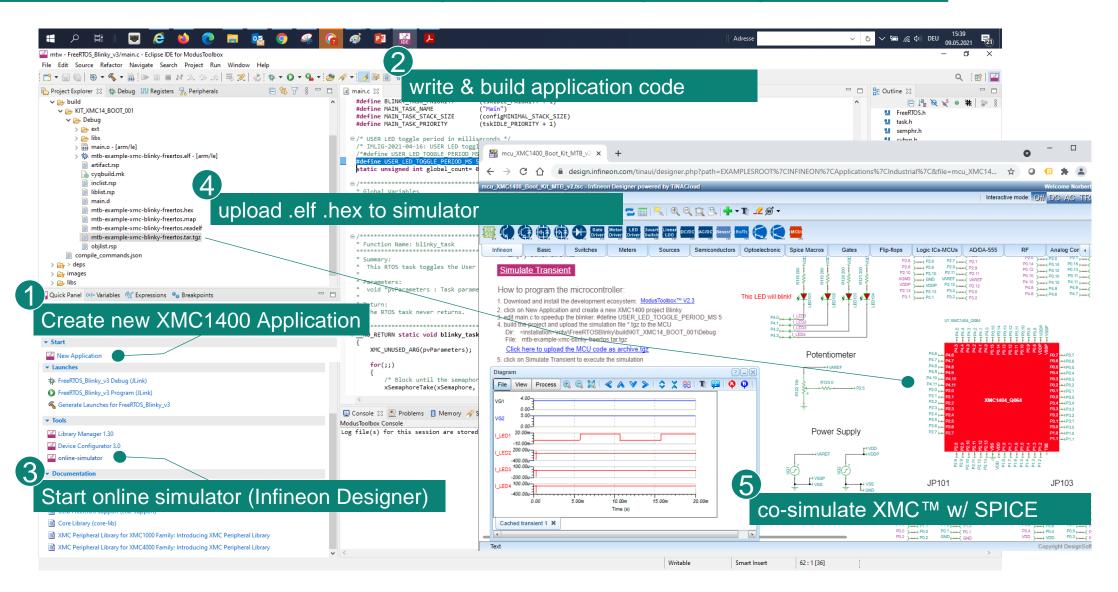
Value Proposition

- Flexible: You can use any IDE in your own workflow (Eclipse, GNU Make, IAR Embedded Workbench, KEIL µVision; Visual Studio Code)
- Cross platform: Linux, macOS, Windows
- GitHub software ecosystem driven by manifests: Create a project with the latest version using Project Creator independent of any IDE and export to any IDE
- Library Manager Add, update, or remove libraries with the Library Manager
- Kit & Board Support: Includes board support packages (BSPs). Every release of every library is readily available
- Tools & Configurators: to set things up Device, CapSense, QSPI, Smart I/O, USB, Bluetooth, Segment LCD

ModusToolbox™ Example



Digital Twin of XMC1400 Boot Kit co-simulating Application Code generated by ModusToolbox™



Simulation: 32-bit XMC1000™ Industrial MCU Arm® Cortex®-M https://www.infineon.com/xmc



ARM® Cortex®-M0

- > Core up to 48 MHz
- > Peripherals up to 96 MHz
- > Wide supply voltage range 2–5 V
- > 12-bit ADC
- > -40 ... +105°C temperature
- > And more...

Universal

XMC1100

ARM® Cortex®-M0 CPU at 32 MHz

Flash: 8–64 kB

Package: 16-40 pins

Lighting

XMC1200

ARM® Cortex®-M0 CPU at 32 MHz Flash: 8–200 kB

Package: 16-40 pins

Main features

- > 9 ch LED control
- 3x analog comparators
- > BCCU LED unit

Motor Control, SMPS

XMC1300

Cortex®-M0 CPU at 32 MHz Flash: 8–200 kB

Package: 16–40 pins

Main features

- > Math co-processor
- > CCU8 PWM timer
- > POSIF encoder
- > Motor control SW

Performance

XMC1400

ARM® Cortex®-M0 CPU at 48 MHz

Flash: 8-200 kB

Package: 40-64 pins

Main features

- > 70% more performance
- > 2x CAN
- > 2x CCU8
- > Up to 4 serial channel
- 4x analog comparators

Integration

Performance

New: 32-bit XMC4400™ Industrial MCU Arm® Cortex®-M https://www.infineon.com/xmc



XMC 4 4 0 0 - F 144 K 1024 AC

Memory				Analog				Timer/PWM					Connectivity						
ARM® Cortex®-M4F	Frequency [MHz]		ADC 12 bit / S&H	Number of channels	DAC 12 bit	CCU4 (4 ch)	CCU8 (4 ch)	HRPWM (150 ps)	POSIF	ΔΣ demodulator	nsıc	CAN2.0B	USB	Ethernet	Ether CAT:	SDIO/SD/MMC	External Bus Unit (EBU)		
XMC41x	80	Flash 64–128 kB RAM 20 kB	2/2	up to 9	2 ch	2x	1x	•	•	-	4x	up to 2	•	-	-	-	-	VQFN-48 TQFP-64	
XMC42x	80	Flash 256 kB RAM 40 kB	2/2	up to 9	2 ch	2x	1x	•	•	-	4x	2x	•	-	-	-	-	VQFN-48 TQFP-64	
XMC43x	144	Flash 256 kB RAM 128 kB	2/2	14	2 ch	2x	1x	-	-	-	4x	2x	•	•	•	•	-	LQFP-100	
XMC44x	120	Flash 256-512 k RAM 80 kB	B 4/4	up to 18	2 ch	4x	2x	•	2x	4 ch	4x	2x	•	•	-	-	-	TQFP-64 LOFP-100	
XMC45x	120	Flash 512 kB-1 N RAM 128-160 k	1 41/4	up to 26	2 ch	4x	2x	-	2x	4 ch	4x	up to 3	•	•	-	•	•	LQFP-100/144 LFBGA-144	
XMC47x	144	Flash 1.5–2 MB RAM 276–352 k	B 4/4	up to 26	2 ch	4x	2x	-	2x	4 ch	6x	6x	•	•	-	•	•	LFBGA-196	
XMC48x	144	Flash 1–2 MB RAM 276–352 k	B 4/4	up to 26	2 ch	4x	2x	-	2x	4 ch	6x	6x	•	•	•	•	•	LQFP-100/144 LFBGA-196	
					Sup	ply v	oltag	e ran	ge 3.1	13 to 3.	63 V								
	Temperature range -40°C 85°C/125°C																		

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ModusToolbox™ replacing DAVE™



Legacy: DAVE™





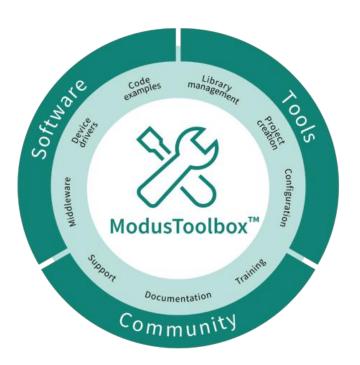
Digital Application Virtual Engineer

- Free Eclipse CDT based IDE using GNU C-Compiler
- Code generation with graphical user interface (GUI) Configurable and reusable code repository consist of **XMC™ Lib** (for all peripherals), DAVE™ APPs, and EXAMPLES
- Automatic assignment of chip resources (resolver)
- Debugger and Flash loader
- All XMC™ MCUs powered by ARM® Cortex®-M supported
- > XMC[™] Lib and DAVE[™] APPs **tested** with GCC compiler, ARM® compiler, and TASKING compiler released for Altium, ARM/KEIL, Atollic, DAVE™, IAR Systems, and Rowley



https://softwaretools.infineon.com/tools?q=dave

New: ModusToolbox™



https://www.infineon.com/modustoolbox

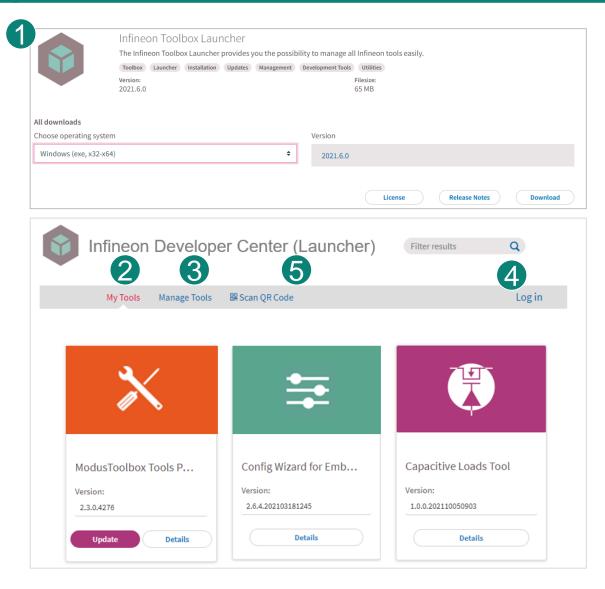
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Step 1: download launcher utility and manage tools https://softwaretools.infineon.com/tools/com.ifx.tb.launcher2

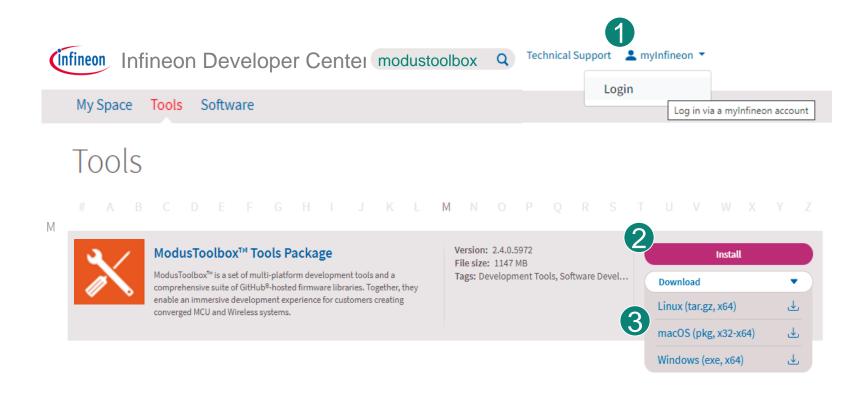




- 1. Install Launcher Utility
- Download and install the Infineon Developer Center launcher (former Toolbox) utility: https://softwaretools.infineon.com/tools/com.i fx.tb.launcher2
- 3. The launcher utility on your computer from the Windows Start menu. It has 3 tabs
- My Tools: here you find all the tools you installed. You start them and get informed about the latest updates
- Manage Tools: here you can download more tools
- 6. Important: please login and allow admin rights before installing a new tool
- Scan QR Code: this is for the registration of evaluation boards and new projects in <u>MySpace</u>

Step 2: install ModusToolbox™ from Infineon Developer Center https://softwaretools.infineon.com/tools/com.ifx.tb.tool.modustoolbox

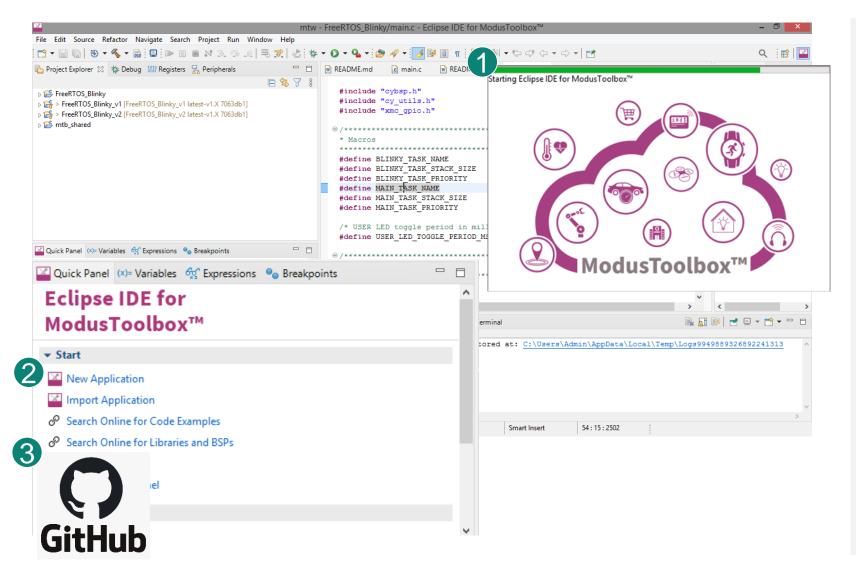




- Important: please login with your myInfineon account and allow admin rights before installing
- Install (recommended): this will install the tool in the launcher utility where you can easily manage all tools and get informed if there is an update
- 3. Download: use this for downloading the installer for another operating system than Windows (e.g., Linux, macOS, etc.)



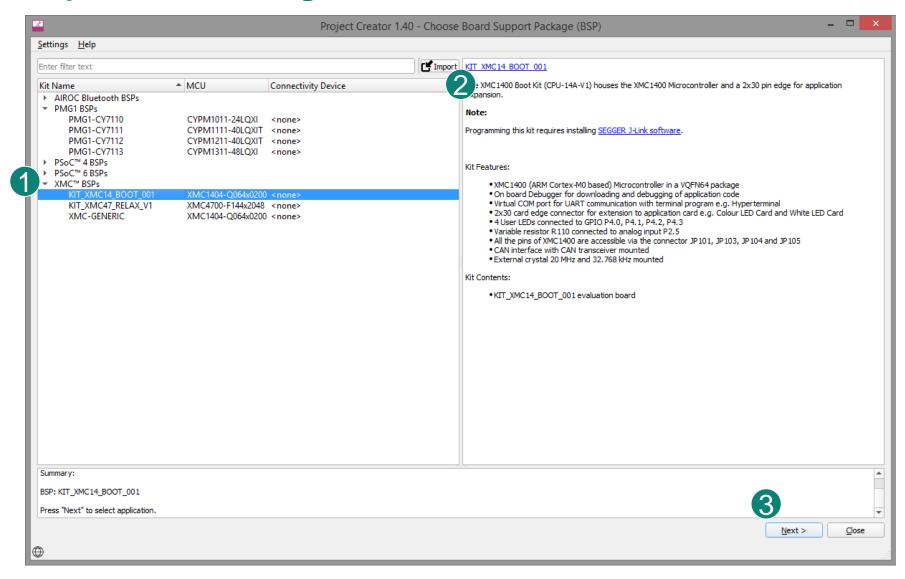
Step 3: start ModusToolbox™ (using Eclipse IDE)



- Start Eclipse IDE with project and start panels
- 2. In Quick Panel under
 Start click on New
 Application which
 opens the Project
 Creator window (please
 look for window in
 background)
- 3. Connection to GitHub to fetch code examples



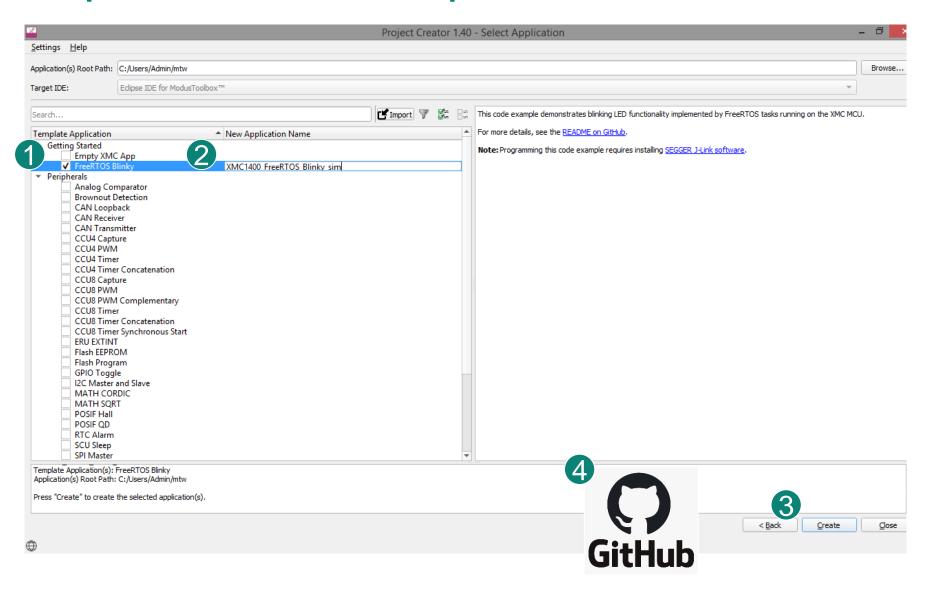
Step 4a: select Target Platform



- Select target platform
 XMC™ Board Support
 Packages (BSP)
- SelectKIT_XMC14_BOOT_001
- 3. Click on Next to select code examples



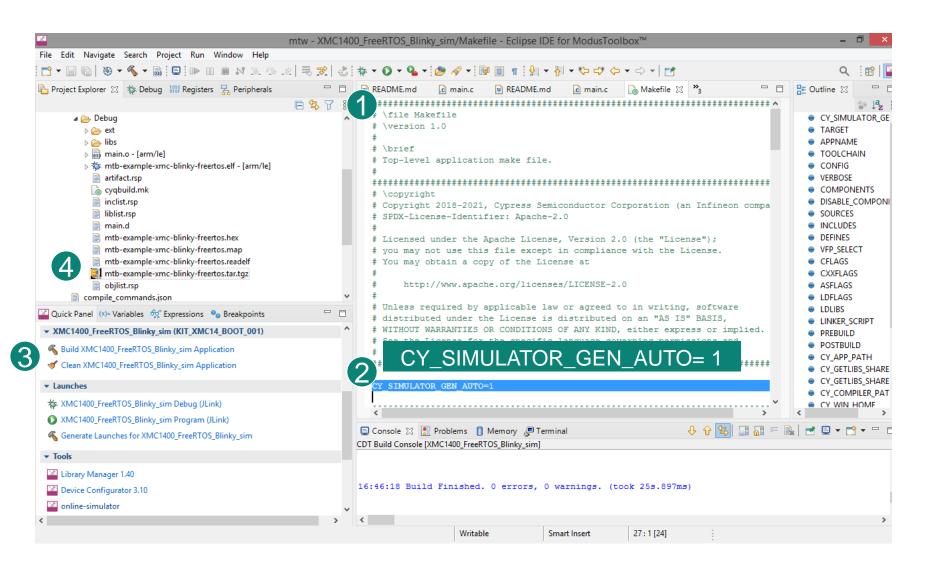
Step 4b: Select Code Example from GitHub



- Select the code example FreeRTOS Blinky
- Set a New Application Name as you like
- 3. Click on Create
- This will take some time since a GitHub clone is done – please wait until

Step 5: wait until GitHub clone is finished – build project Makefile: Set CY_SIMULATOR_GEN_AUTO= 1

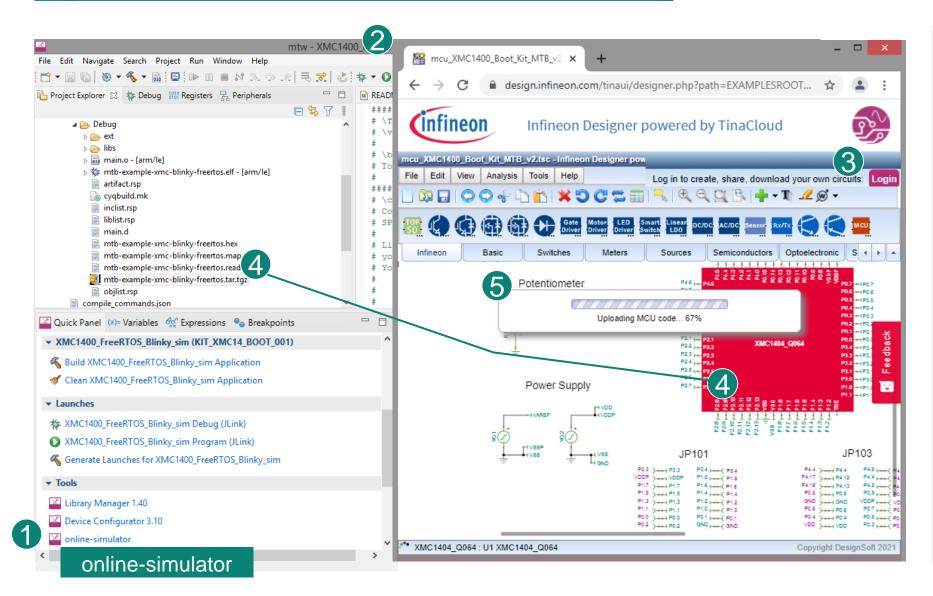




- 1. Open Makefile
- Set value for generation of simulation image CY_SIMULATOR_GEN_ AUTO= 1
- 3. Speed-up blinking of LFD to 5 ms
- 4. Build project
- In Debug folder the image has been created
- 6. Resut: Mtb-examplexmc-blinkyfreertos.tar.tgz

Step 6: start Infineon Designer simulator – upload code <u>Digital Twin of XMC1400 Boot Kit co-simulating</u>

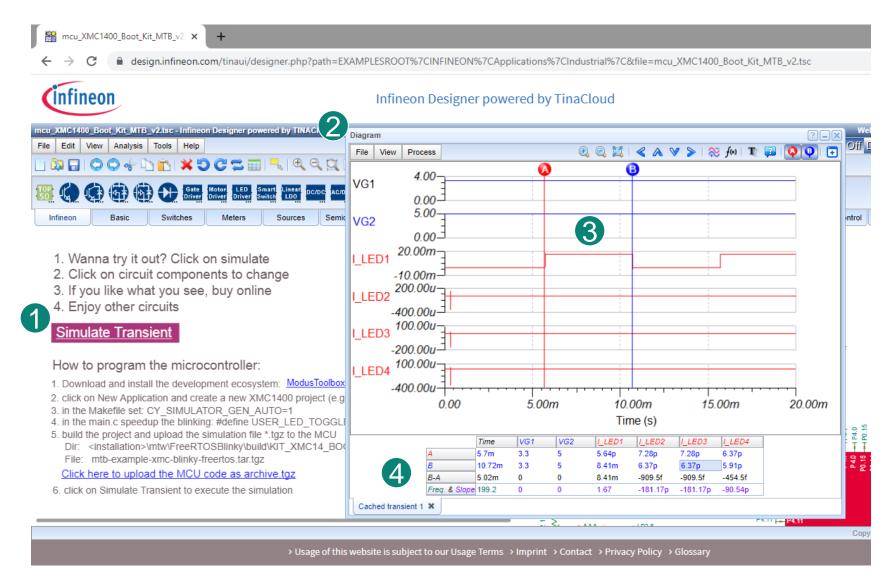




- In Quick Panel under Tools click on onlinesimulator
- It will open the online simulation kit: <u>Digital</u>
 <u>Twin of XMC1400 Boot Kit co-simulating</u>
- 3. Please <u>login</u> in order to upload code
- Drag and drop .tar.tgz image on XMC microcontroller
- 5. Upload code



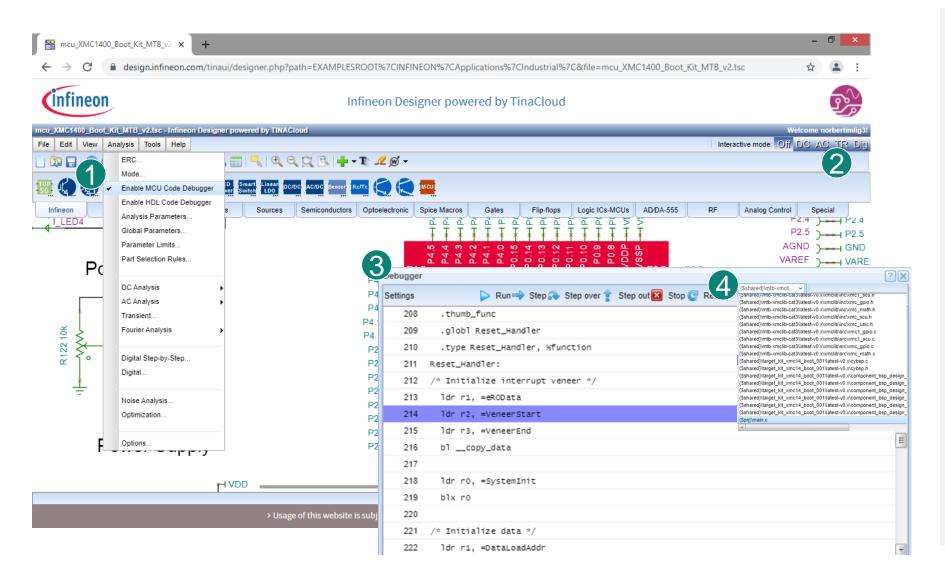
Step 7: simulate Transient and check result



- Click on simulate
 Transient to start the simulation
- Check the results in the diagram window
- Resutl: I_LED1 toggles in 5 ms
- 4. Use curser to verify other signal



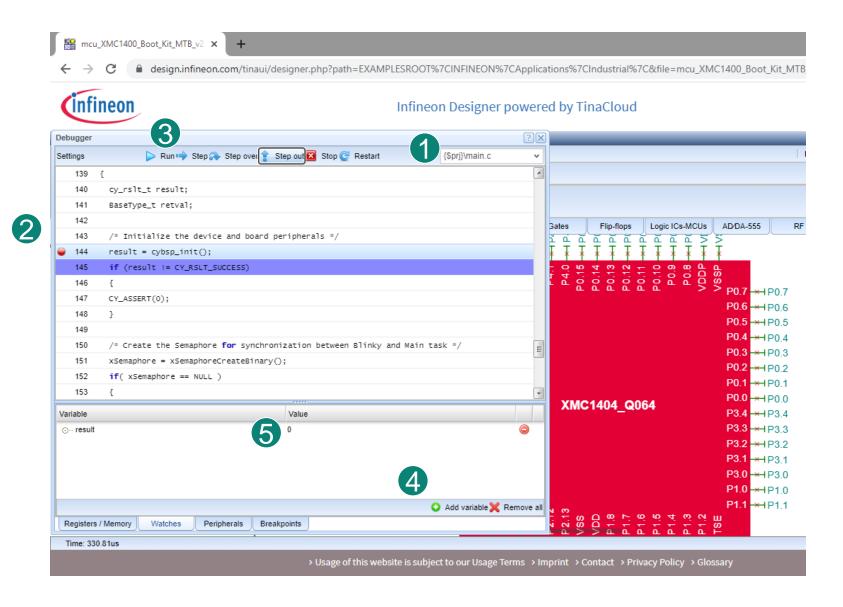
Step 8: debug code in interactive mode



- Select the Analysis menu and Enable MCU Code
 Debugger
- Click on TR to start interactive mode
- Wait until debugger window opens
- 4. Inspect code in files



Step 9: set breakpoints and inspect variables



- 1. Select main.c
- 2. Set breakpoint
- 3. Run to breakpoint
- 4. Add variable
- Inspect variable result=

Step 10: select other circuits https://www.infineon.com/ifxdesigner





Inverter OptiMOS™ BSC0925ND and

Infineon Designer – Online SPICE Simulator

Infineon Designer is the first online prototyping engine combining analog and digital simulation functionalities in an internet application. Requiring a web browser only, it is a perfect match for supporting customers in selecting the right product for a defined application. Infineon Designer works intuitively in a very short time, and neither installation nor licenses are needed. Please start with one of the following application circuits.

Infineon Designer is powered by TINACloud the online circuit analyzer of DesignSoft. You can upgrade to the full version of > TINACloud or its offline version > TINA here; > https://www.tina.com/tinaupgrade

Showing 1 to 25 of 25 entries (filtered from 750 total entries) **Product Configuration** Description \$ Circuit **♦** Application **♦** Product Category ♦ Reset All Select v Select Digital Twin of XMC1400 Boot Kit co-LED lighting simulating Embedded Application Code Motor XMC1404-Q064X0200 AA generated by ModusToolbox™ control Microcontroller Read more KIT_XMC14_BOOT_001 Development Ecosystem along with Power analog SPICE circuits supplies Brushless DC (BLDC) Motor controlled by Sensorless Field-Oriented Control XMC1302-T038X0200 AB Motor (FOC) using XMC1302 32-bit ARM® Microcontroller Read more KIT_XMC1X_AK_MOTOR_001 control Cortex®-M0 microcontroller (Ideal Inverter) Brushless DC (BLDC) Motor controlled XMC1302-T038X0200 AB by Sensorless Field-Oriented Control Microcontroller BSC0925ND (FOC) using XMC1302 with MOSFET Motor

MOSFET

control

IR2301



Read more

- Open landing page <u>https://www.infineon.co</u>
 <u>m/ifxdesigner</u>
- Search for XMC circuit in table
- Select BLDC motor example with FOC control running on XMC1302

Exercise: Brushless DC (BLDC) Motor controlled by Sensorless Field-Oriented Control (FOC) using XMC™ microcontroller

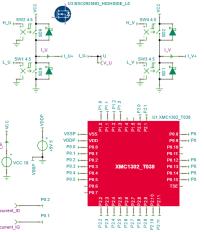


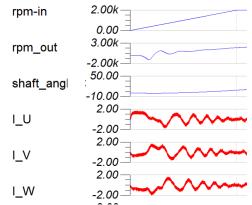




Simulate Transient

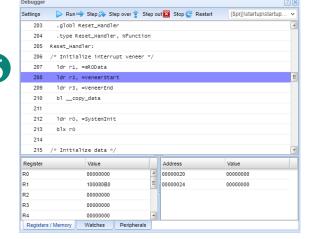












J=3.5u
B=1u
F=1u
D=1u
A=8
P=3
CL=3865u
CR=6.8
CC=0.001u
CM=0.5
Cb=49m
Ct=49m
r_snub=1k*2*pi*Cl

.param J Moment of interia. Unit: kg*m^2
.param B Damping end eddy current losses. Unit: kg*m^2/(s*rad)
.param F Friction / drag losses. Unit: kg*m^2/s^2
.param D Magnetic cogging torque. Unit: kg m^2/s^2
.param A Number of north poles
.param P Number of phases
.param CL Winding inductance
.param CR Winding resistance
.param CC winding capacitance to ground
.param CM adjacent winding mutual coupling factor
.param Cb; BEMF constant. Unit: V*s/rad
.param Ct Torque constant. Unit: N*m/A
.param r_snub = 1k*2*pi*CL

- 1. open application circuit: <u>Brushless DC (BLDC) Motor controlled by Sensorless Field-Oriented Control (FOC) using XMC1302 32-bit ARM® Cortex®-M0 microcontroller (Ideal Inverter)</u>
- simulate the circuit using Simulate Transient
- 3. check the results
 - rpm ramp-up/ramp-down profile
 - 3 phase currents
- 4. Enable the debugger mode
 - Analysis -> Enable MCU Code Debugger
 - View -> Preference -> Draw diagram in interactive mode
 - In the task bar: start the debugger window by click on Interactive mode: TR

Your task

- Step through the code and select the main.c file and set a breakpoint in main() function
 - run to the breakpoint
 - add variables in the watch window
 - temperature dependency
- 5. Change the motor parameter to your needs and simulate again

Bonus task

- Install DAVE™ IDE software and change the FOC code examples
- Simulate with real MOSFETs <u>Brushless DC (BLDC) Motor controlled by Sensorless Field-Oriented Control (FOC) using XMC1302 with MOSFET Inverter OptiMOS™</u>
 BSC0925ND and high-side and low-side Gate Driver IC IR2301
- Explore stepper motor example: <u>Stepper Motor Control Shield with IFX9201 & XMC1300 using Fullstep</u>, Halfstep or Microstepping modes
- Simulate PINUS Multicopter Board V2 with XMC1100, IR2301 and BSC0925ND

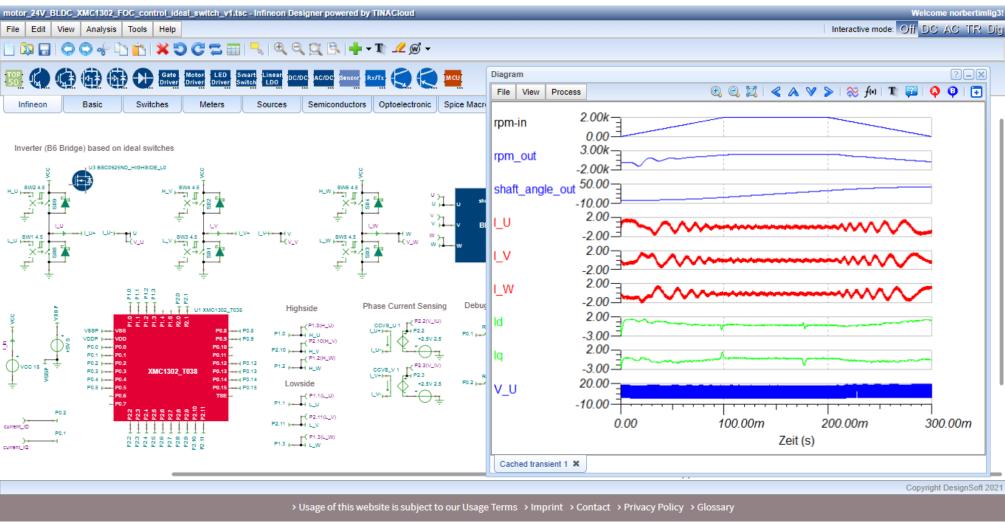
Exercise: Brushless DC (BLDC) Motor controlled by Sensorless Field-Oriented Control (FOC) using XMC1302





Infineon Designer powered by TinaCloud







Demo & Exercise Summary

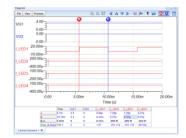
- Demo: we installed ModusToolbox™ and used the code example Blinky based on the real time FreeRTOS
 - set value for generation of simulation image
 SIMILATOR GENERATION 1
 - CY_SIMULATOR_GEN_AUTO= 1
 - speed-up blinking of LED to 5 ms
 - started the online simulation circuit <u>Digital Twin of XMC1400 Boot Kit co-simulating</u>
 - uploaded the generate .elf/.hex image Mtb-example-xmc-blinky-freertos.tar.tgz
 - started a transient simulation
 - Results:
 - verified blinking LED of 5ms with cursor
 - verified uploaded code by starting interactive debugger
 - Conclusion: Digital co-simulation has many advantages as reducing a) Time-to-market: start developing before you have the hardware kit, b) Safety: test on virtual system will not harm engineer or destroy hardware, c) cost: exploration of design space cheaper than building hardware many times
- Exercise: Brushless DC (BLDC) Motor controlled by Sensorless Field-Oriented Control (FOC) using XMC™ microcontroller
 - you co-simulated the software FOC code running on an XMC™ microcontroller
 - you debugged the code compiled by DAVE™
 - Infineon Designer (SPICE) is the tool of choice when co-simulating analog and digital microcontroller
 - All Simulation models are available for download on the product pages
- Where to go from here
 - Install DAVE™ IDE software and change the FOC code examples
 - Simulate with real MOSFETs <u>Brushless DC (BLDC) Motor controlled by Sensorless Field-Oriented Control (FOC) using</u>
 XMC1302 with MOSFET Inverter OptiMOS™ BSC0925ND and high-side and low-side Gate Driver IC IR2301













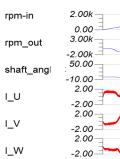


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infineon

Tips & Tricks

Enlarge the editor area

Edit circuit

Search text

Solve artifacts

Import additional SPICE models

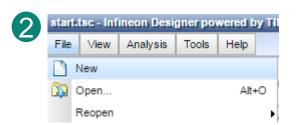
More features offline

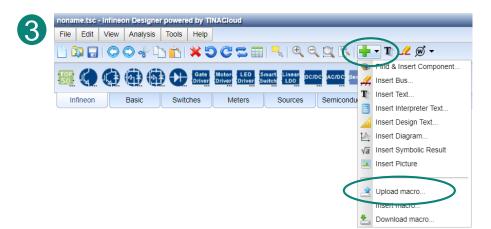
- Menu >> View >> Full-screen (full-screen & remove banner)
- > F11 (Browser full-screen)
- Component view
- > Zoom-in/out: mouse scroll, or key [Shift 1] + drag for zoom-in
- Wire connection: see demonstration
- Multi-selection: see demonstration
- Circuit view shifting: see demonstration
- Key combination [Ctrl] + [F]
 - Search components in circuit editor
 - Search variable in design tool editor
- browser and server caching issues
 - revert to original (Menu >> File >> Revert to original)
 - change language (Menu >> View >> Language)
- > First menu bar ->> Upload macros...
- Then menu bar +>> Insert macros...
- Menu >> Help >> Order or Upgrade...
- Upgrade to TINA Industrial offline version: www.tina.com

How To Import A SPICE Model (Part 1/2)













- 1. <u>Login</u> with your myInfineon account
- 2. Select File -> New, create a new circuit
- 3. Click menu bar symbol and click "Upload macro..."
- 4. Name your model, select "from file", and browse to your SPICE model in .SUBCKT format
- 5. Click on "Upload"

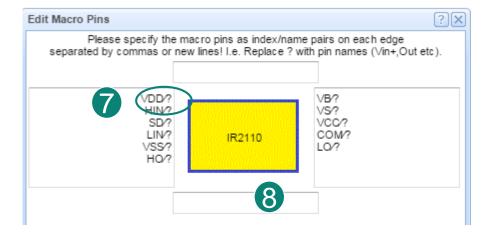
Example Model OrCAD Capture for IR2110

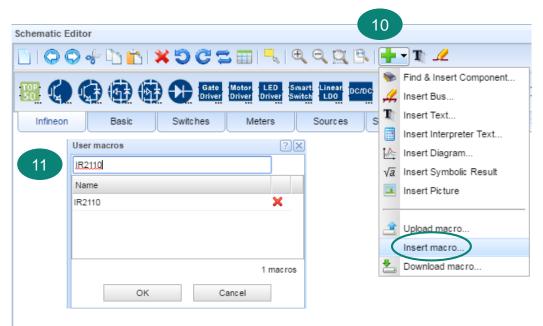
```
.SUBCKT IR2110 VDD HIN SD
LIN VSS HO VB VS VCC COM
LO
+PARAMS:
+ T1=-40 T2=25
T3=125
...
.ENDS IR2110
```

How To Import A SPICE Model (Part 2/2)

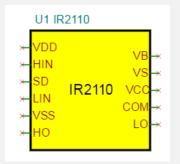








- 1. Edit symbol pin layout
- 2. Optional: Replace "?" with new pin name in symbol Example: VDD/? -> VDD/VDD
 - Optional: place pins on top, left, right, bottom
- 4. Click on OK to upload macro
- 5. Click menu bar symbol and click "Insert macro..."
- 6. Select IR2110 macro and place it on your schematic



- 7. Finalize your circuit and Save it with "Save -> Save as"
- 8. Test your circuit
- 9

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Thank you an see you soon in our next webinar https://www.infineon.com/cms/austria/en/IPCEI-on-ME





Infineon Technologies Austria – Part of IPCEI Microelectronics

Infineon's power semiconductors are deployed in key markets such as automotive, energy, digital and industrial equipment. These power electronics solutions also drive innovation in environmental sustainability, energy-efficiency and reduction of CO₂ emissions.

Infineon's IPCEI spillover activities include the following areas:

STEM education and talent
 Infine on Austria will actively involve educational institutions and STEM talent, from pupils to PhDs.





















2				
S	Event	Date	Time	
	Microcontroller Co-Simulation	18.10.2023	10:00 - 11:00	> More information
			New time!	
	Digital Power Supply Simulation	18.10.2023	11:00 - 12:00	> More information
			New time!	
	Online LCC development tool	28.11.2023	13:00 - 14:00	> More information

Quick design of a flyback converter	28.11.2023	14:00 - 15:00	> More information
Application driven development Part I: USB-PowerDelivery	13.12.2023	14:00 - 15:00	> More information
Application driven development Part II: Embedded Coding	13.12.2023	15:00 - 16:00	> More information
Application driven development Part III: Cloud Co-Simulation	13.12.2023	16:00 - 17:00	> More information





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